

# Programmeren (Ectrie)

## Lecture 4: Program correctness

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# Counting sum of the elements of an integer array

```
public static int countSum(int [] array) {  
    for (int i=1;i<array.length;i++) {  
        array[i] = array[i] + array[i-1];  
    }  
    return array[array.length-1];  
}
```

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}
```

- Returns the correct value, but also modifies the parameter array as a *side effect*.
- What would you expect from:

```
public static int countSum(int [] array)
```

- Unexpected side effects make code difficult to understand
- There are also *desired* side effects, e.g. sorting the contents of an array
- In Java we have
  - Accessor methods: returning a value but not modifying contents of the object (`public int getAge()`)
  - Mutator methods: modifying the contents of the object but not returning a value (`public void setAge(int age)`)

- In imperative programming, we similarly classify methods into
  - **Functions**, that return a value but do not alter the parameters in any way
  - **Procedures**, that alter some of the parameters but do not return a value

```
void setElement(Matrix m, int rInd , int cInd ,  
    double newElement)
```

```
double getElement(Matrix m, int rInd , int cInd)
```

- Note: if the language does not support exceptions (e.g. C), procedures often do return a value for signifying error conditions

# Parameter passing schemes

- For side effects to be possible, parameters have to be passed *by reference*: only a reference (memory address) of the variable is passed to the called method
- Other main technique for parameter passing is to pass *by value*: a local copy of the variable is created within the called method
- Example: pass by reference vs pass by value

# Parameter passing schemes

- For side effects to be possible, parameters have to be passed *by reference*: only a reference (memory address) of the variable is passed to the called method
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- Example: pass by reference vs pass by value
- Matlab passes everything by value, although:
  - Matrices are passed by references until they are modified the first time, at which point a local copy is created (!)
  - The OO-extension allows to pass references by value by using the handle class

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- Pros:
  - No undesired side effects
- Cons:
  - No desired side effects
  - Many algorithms can be expressed more clearly with procedures
  - Recursive algorithms become slow without procedures

```
function A = sort(A)
    leftList = A(1:middle);
    rightList = A((middle+1):length(A));
    leftList = sort(leftList);
    rightList = sort(rightList);
    A = merge(leftList , rightList);
end
```

- When you design methods, there is a *contract* between the supplier (you) and the consumer (possibly someone else)
- The contract can be partially defined by the signature:

```
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Contract:

- 1 The `index` has to be in the range `[1, length(array)]`  
(responsibility of the consumer)
- 2 If consumer calls the method adhering to (1), then after the method call the following holds:  
`array[index] < array[index+1] < ... <`  
`array[length(array)]` (responsibility of the supplier)

```
% Sorts the array in ascending order starting  
% from index  
%  
% PRECOND:  $0 < index \leq length(array)$   
% POSTCOND:  $arr(index) < \dots$   
%  $\dots < arr(length(array))$   
function arr = sortArrayFromIndex(array, index)
```

- Responsibilities of the consumer are method *pre-conditions* (“Requires”)
- Responsibilities of the supplier are method *post-conditions* (“Ensures”)
- (PRECOND, METHOD)  $\Rightarrow$  POSTCOND

# Violating pre-conditions

- As a supplier, if the pre-condition is violated, you are not responsible for what happens
- In practice you should crash the program execution, as the mistake is in the logic

```
function array = sortFromIndex(array , index)  
    assert(index > 0 && index <= length(array));  
    ... % do the actual sorting  
end
```

# When to use pre- and post-conditions

- If you cannot handle a possible parameter value, you should declare the accepted range as a pre-condition
- Post-conditions are often stated in a more informal manner in the method documentation
- Document post-conditions when doing more complex programs, and when you have problems finding bugs

$(\text{PRECOND}, \text{METHOD}) \Rightarrow \text{POSTCOND}$

How do we know that METHOD ever terminates execution?  
How do we know that METHOD does what it's supposed to?

# Stop or not?

```
for (i=1:10)
    printf("%d th integer\n", i);
end
```

---

```
nr = input("How many integers you want?");
for (i=1:nr)
    printf("%d th integer\n", i);
    sleep(10*i);
end
```

---

```
green = true;
while(green)
    green = false;
    sleep(10);
    green = true;
end
```



# Alan Turing (1912-54)



- Designed the computer that cracked German Enigma in WW2
- Invented LU decomposition
- Invented the Turing test
- Proved the following

# The halting problem

Given a program  $P$  with input  $I$ , let us assume that there is another program  $H(P, I)$ , that outputs

- “halt”, if  $P$  stops with input  $I$
- “loop”, otherwise

Given that we have von Neumann computers (programs = data), we can also call  $H(P, P)$

# The halting problem

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Given that  $K$  is a program, we can use it as the input to  $K$ . Now:

- if  $H$  says that  $K$  halts, then  $K$  itself would loop
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⇒ the halting problem is undecidable.

We cannot algorithmically determine whether a program stops execution

# Proving that program terminates

- Structures causing infinite computation are iteration and (mutual) recursion
- Recursion can always be converted to iteration
- Proof of termination is done similarly to induction:
  - Integer iteration counter  $i$  starts at value  $i_0$
  - Iteration ends when  $i > i_x$
  - In each iteration,  $i$  increases by value  $> 0$

# Proving that iteration computes the correct result

```
int i=1;
maxV = array(1);
while(i < length(array))
    if (maxV < array(i+1))
        maxV = array(i+1);
    end
    i = i+1;
end
```



- Loop invariants describe a condition that holds
  - In the beginning of the iteration
  - At the end of each iteration

# Loop invariants for max element of an array

```
int i=1;
maxV = array(1);
% invariant: maxV = largest of array[1..i]
while(i < length(array))
    if (maxV < array(i+1))
        maxV = array(i+1);
    end
    i = i+1;
end
```

- Easy to show that the loop terminates

```

%Sorts array in ascending order from index on
%
%PRECOND: 0 < index <= length(array)
%POSTCOND: array(index) < ... < array(length(array))
function array = insSortFromIndex(array, index)
    assert(index > 0 && index <= length(array));
    % loop invariant: array[index..j] is sorted
    for j=index:length(a)
        key = array(j);
        i = j-1;
        while i > index && array(i) > key
            array(i+1) = array(i);
            i = i-1;
        end
        array(i+1) = key
    end
end

```